## Flight test report

Manufacturer ADVANCE Thun AG

Address Seestrasse 14 3602 Thun Switzerland

Representive Kari Eisenhut
Type of glider Alpha 4 31
Trimmer not available

 Certification number
 PG 062.2007

 Date of flight test
 24/04/2007

 Place of test
 Villeneuve



## Classification B

Test Pilot Claude Thurnheer Harness Gin Genie III

Total weight in flight 104 kg

Alain Zoller

Advance - Progress L

130 kg

|                  |   | Min weight   | Max weight  |
|------------------|---|--|---|
| 1. Inflation/Ta  |   |  |   |
|                  | Rising behaviour Special take off technique required                |  | A Smooth, easy and constant rising A No A                                 |
| 2. Landing       | On a stable and the stable to the state of                          | Al-  | A No.   |
| 3. Speed in st   | Special landing technique required                                  | No /   | A No A  |
| o. opeeu iii si  | Trim speed more than 30 km/h  | Yes  | A Yes A   |
|                  | Speed range using the controls larger than 10 km/h                  | Yes  | A Yes A   |
|                  | Minimum speed   | Less than 25 km/h  | A Less than 25 km/h A   |
| 4. Control mo    |   |  |   |
|                  | Max. weight in flight up to 80 kg Symmetric control pressure/travel | not available  | 0 not available 0   |
|                  | Max. weight in flight 80 kg to 100 kg                               | not available  | o not available   |
|                  | Symmetric control pressure/travel                                   | not available  | 0 not available 0   |
|                  | Max. weight in flight greater than 100 kg                           |  |   |
| . Birele erelii  | Symmetric control pressure/travel                                   | Increasing, Greater than 65 cm   | Increasing, Greater than 65 cm A  |
| . Pitch Stabil   | ity exiting accelerated flight Dive forward angle on exit           | Dive forward less than 30°   | A Dive forward less than 30° A  |
|                  | Collapse occurs   |  | A No A  |
| . Pitch stabil   | ity operating controls during accelerated flight                    |  |   |
|                  | Collapse occurs   | No /   | A No A  |
| . Roll stabilit  | y and damping   | Dadusina   | ) Deducies  |
| Stability in     | Oscillations gentle spirals   | Reducing   | A Reducing A  |
| o. Glability III | Tendency to return to straight flight                               | Spontaneous exit   | A Spontaneous exit A  |
| . Behaviour      | in a steeply banked turn  | ,  | \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \                                     |
|                  | Sink rate after two turns   | Up to 12m/s  | A More than 14 m/s B  |
| 0. Symmetric     | c front collapse  | 5 11 1 11 11 15  |   |
|                  | Entry   | 3  | A Rocking back less than 45° A Spontaneous in less than 3 s A             |
|                  | Recovery Dive forward angle on exit                                 |  | A Spontaneous in less than 3 s A A Dive foward 0°to 30°, Keeping course A |
|                  | Cascade occurs  | 3  | A No A  |
|                  | With accelerator  |  |   |
|                  | Entry   |  | A Rocking back less than 45° A  |
|                  | Recovery  | The state of the s | A Spontaneous in less than 3 s A Dive foward 0°to 30°, Keeping course A   |
|                  | Dive forward angle on exit Cascade occurs                           | Dive foward 0°to 30°, Keeping course No  |   |
| 1. Exiting de    | ep stall (parachutal stall)   | ,  |   |
| _                | Deep stall achieved   | Yes  | A Yes A   |
|                  | Recovery  |  | A Spontaneous in less than 3 s A  |
|                  | Dive forward angle on exit<br>Change of course                      | Dive forward 0°to 30° Changing course less than 45°  | A Dive forward 0°to 30° A A Changing course less than 45° A               |
|                  | Cascade occurs  |  | A No A  |
| 2. High angle    | e of attack recovery  |  |   |
|                  | Recovery  |  | A Spontaneous in less than 3 s A  |
|                  | Cascade occurs  | No /   | A No A  |
| 3. Recovery      | from a developed full stall Dive forward angle on exit              | Dive forward 0°to 30°  | A Dive forward 0°to 30° A   |
|                  | Collapse  |  | A No collapse A   |
|                  | Cascade occurs (other than collapse)                                | No /   | · ·   |
|                  | Rocking back  | Less than 45°  | A Less than 45° A   |
|                  | Line tension  | Most line tight  | A Most line tight A   |
| 4. Asymmeti      | ric collapse With 50% collapse-Maximum dive forward or roll angle   |  |   |
|                  | Change of course until re-inflation                                 | Less than 90°, Dive or roll angle 0° to 15°  | Less than 90°, Dive or roll angle 0° to 15° A                             |
|                  | Re-inflation behaviour  |  | A Spontaneous re-inflation A  |
|                  | Total change of course  | Less than 360°   | Less than 360° A  |
|                  | Collapse on the opposite side occurs                                |  | A No A  |
|                  | Twist occurs  |  | A No A  |
|                  | Cascade occurs With 75% collapse-Maximum dive forward or roll angle | No /   | A No A  |
|                  | Change of course until re-inflation                                 | Less than 90°, Dive or roll angle 15° to 45°   | Less than 90°, Dive or roll angle 0° to 15° A                             |
|                  | Re-inflation behaviour  | and the control of th | A Spontaneous re-inflation A  |
|                  | Total change of course  |  | A Less than 360° A  |
|                  | Collapse on the opposite side occurs                                |  | A No A  |
|                  | Twist occurs Cascade occurs   |  | A No A A No A   |
|                  | With 50% collapse and accelerator-Maximum dive forward or           |  | A   |
|                  | Change of course until re-inflation                                 | · · · · · · · · · · · · · · · · · · ·  | Less than 90°, Dive or roll angle 0° to 15° A                             |
|                  | Re-inflation behaviour  |  | A Spontaneous re-inflation A  |
|                  | Total change of course  |  | A Less than 360° A  |
|                  | Collapse on the opposite side occurs                                | No /   | A No A  |

|                | Twist occurs  | No   | Α | No   | Α |  |  |
|----------------|---|--|---|--|---|--|--|
|                | Cascade occurs  | No   | Α | No   | Α |  |  |
|                | With 75% collapse and accelerator-Maximum dive forward o    |  |   |  |   |  |  |
|                | Change of course until re-inflation                         | Less than 90°, Dive or roll angle 15° to 45°   | Α | 90° to 180°, Dive or roll angle 0° to 15°      | Α |  |  |
|                | Re-inflation behaviour                                      | Spontaneous re-inflation                       | Α | Spontaneous re-inflation                       | Α |  |  |
|                | Total change of course                                      | Less than 360°                                 | Α | Less than 360°                                 | Α |  |  |
|                | Collapse on the opposite side occurs                        | No   | Α | No   | Α |  |  |
|                | Twist occurs  | No   | Α | No   | Α |  |  |
|                | Cascade occurs  | No   | Α | No   | Α |  |  |
| 15. Directiona | al control with a maintained asymmetric collapse            |  |   |  |   |  |  |
|                | Able to keep course   | Yes  | Α | Yes  | Α |  |  |
|                | 180° turn away from the collapsed side possible in 10 s     | Yes  | Α | Yes  | Α |  |  |
|                | Amount of control range between turn and stall or spin      | More than 50 % of the symmetric control travel | Α | More than 50 % of the symmetric control travel | Α |  |  |
| 16. Trim spee  | ed spin tendency  |  |   |  |   |  |  |
|                | Spin occurs   | No   | Α | No   | Α |  |  |
| 17. Low spee   | d spin tendency   |  |   |  |   |  |  |
|                | Spin occurs   | No   | Α | No   | Α |  |  |
| 18. Recovery   | from a developed spin                                       |  |   |  |   |  |  |
|                | Spin rotation angle after release                           | Stops spinning in less than 90°                | Α | Stops spinning in less than 90°                | Α |  |  |
|                | Cascade occurs  | No   | Α | No   | Α |  |  |
| 19. B-line sta | II .  |  |   |  |   |  |  |
|                | Change of course before release                             | Change of course less than 45°                 | Α | Change of course less than 45°                 | Α |  |  |
|                | Behaviour before release                                    | Remains stable with straight span              | Α | Remains stable with straight span              | Α |  |  |
|                | Recovery  | Spontaneous in less than 3 s                   | Α | Spontaneous in less than 3 s                   | Α |  |  |
|                | Dive forward angle on exit                                  | Dive forward 0° to 30°                         | Α | Dive forward 0° to 30°                         | Α |  |  |
|                | Cascade occurs  | No   | Α | No   | Α |  |  |
| 20. Big ears   |   |  |   |  |   |  |  |
|                | Entry procedure   | Dedicated controls                             | Α | Dedicated controls                             | Α |  |  |
|                | Behaviour during big ears                                   | Stable flight                                  | Α | Stable flight                                  | Α |  |  |
|                | Recovery  | Spontaneous in less than 3 s                   | Α | Spontaneous in less than 3 s                   | Α |  |  |
|                | Dive forward angle on exit                                  | Dive forward 0° to 30°                         | Α | Dive forward 0° to 30°                         | Α |  |  |
| 21. Big ears i | 21. Big ears in accelerated flight                          |  |   |  |   |  |  |
|                | Entry procedure   | Dedicated controls                             | Α | Dedicated controls                             | Α |  |  |
|                | Behaviour during big ears                                   | Stable flight                                  | Α | Stable flight                                  | Α |  |  |
|                | Recovery  | Spontaneous in less than 3 s                   | Α | Spontaneous in less than 3 s                   | Α |  |  |
|                | Dive forward angle on exit                                  | Dive forward 0° to 30°                         | Α | Dive forward 0° to 30°                         | Α |  |  |
|                | Behaviour immediately after releasing the accelerator while | Stable flight                                  | Α | Stable flight                                  | Α |  |  |
| 22. Behaviou   | r exiting a steep spiral                                    |  |   |  |   |  |  |
|                | Tendency to return to straight flight                       | Spontaneous exit                               | Α | Spontaneous exit                               | Α |  |  |
|                | Turn angle to recover normal flight                         | Less than 720°,spontaneous recovery            | Α | Less than 720°,spontaneous recovery            | Α |  |  |
|                | Sink rate when evaluating spiral stability [m/s]            | 18 m/s   |   | 15 m/s   |   |  |  |
| 23. Alternativ | re means of directional control                             |  |   |  |   |  |  |
|                | 180° turn achievable in 20 s                                | Yes  | Α | Yes  | Α |  |  |
|                | Stall or spin occurs  | No   | Α | No   | Α |  |  |
| 24. Any other  | flight procedure and/or configuration described in the us   | er's manual                                    |   |  |   |  |  |
|                | Procedure works as described                                | not available                                  | 0 | not available                                  | 0 |  |  |
|                | Procedure suitable for novice pilots                        | not available                                  | 0 | not available                                  | 0 |  |  |
|                | Cascade occurs  | not available                                  | 0 | not available                                  | 0 |  |  |
| Comments of    | f test pilot  |  |   |  |   |  |  |
|                |   |  |   | no   |   |  |  |
|                | Comments  | no   |   | 110  |   |  |  |



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